## B.E.(with Credits)-Regular-Semester 2012 - Electronics Engineering Sem IV EN 405 - Basic Electrical Machines

P. Pages : 2 Time : Three Hou			★ 4 0 2 3 ★	<b>GUG/W/16/3908</b> Max. Marks : 80	
	Notes	s: 1. 2. 3. 4. 5.	All questions carry equal marks. Due credit will be given to neatness and adequate dimensions. Assume suitable data wherever necessary. Illustrate your answers wherever necessary with the help of neat Non programmable calculator are permitted.	sketches.	
1.	a)	equivale	e equivalent circuit of a single phase transformer and hence appro- ont circuit refer to the primary side also draw the vector diagram we mer is loaded with inductive load.		
	b)	data O.C. tes S.C. test	he equivalent circuit of a 200/400V, 50Hz, 1 φ transformer from the t 200V, 0.7A, 70W – on L.V. side t 15V, 10A, 85W – on H.V. side t the secondary voltage when delivering 0.8 p.f. lagging when the <b>OR</b>		
2.	a)	O.C. test S.C. test Determi i) the ii) the	ng results were obtained on a 50KVA, 2400/120V transformer. t: 396W, 9.65A,120V – on L.V. side :: 810W, 20.8A, 92V – on H.V. side	8	
	b)	Explain of transf	open circuit test and short circuit test to determine equivalent circ	uit parameters 8	
3.	a)	Explain	the different types of generators according to excitation of field w	vinding. 8	
	b)	A four pole lap wound dc shunt generator has a Useful flux per pole of 0.07wb the armature winding consist of 220 turns each of $0.004\Omega$ resistance. Calculate the terminal voltage when running at 900 r.p.m. if the armature current is 50AMP.			
			OR		
4.	a)	speed is i) Wi	nerator has an emf of 100V when the Useful flux per pole is 20 m 800 RPM. Calculate the generated emf th the same flux and the speed of 1000 RPM. th a flux per pole of 24 mWb and a speed of 900 RPM.	Wb and the 8	
	b)	Explain	the concept of Armature reaction in dc generator and its effect.	8	

In dc shunt motor directly proportional to armature current. i) ii) In dc series motor directly proportional to armature current. Explain the methods of speed control of dc shunt motor 8 b) flux control method i) ii) armature voltage control method OR A 250 V shunt motor has a armature current of 20 Amp when running at 1000 rpm against 6. a) 8 full load torque the armature resistance is 0.5  $\Omega$ . What resistance must inserted in series with the armature to reduced to speed 500 rpm as the same torque and what will be the speed if the load torque halved with this resistance in the circuit assume the constant flux throughout and neglect brush drop. Explain the methods of speed control of dc series motor with suitable connection diagram. b) 8 7. Explain the torque speed characteristics of  $3\phi$  Induction motor and the effect of varying 8 a) total resistance on starting and maximum torque. b) A 3 function motor has a 4 pole star connected stator winding the motor runs at 50Hz 8 supply with 200V between slipring the rotor resistance and standstil rotor reactance per phase are 0.1  $\Omega$  and 0.9  $\Omega$  respectively the ratio of rotor to stator turns is 0.67. Calculate Total torque at 4% slip i) Maximum torque ii) iii) Speed at maximum torque iv) Maximum mechanical power OR 8. a) A 4 pole 50Hz, 7.46kw, 3 Induction motor at rated Voltage and frequency has a starting 8 torque of 160% and maximum torque of 200% of full load torque determine full load speed and speed at maximum torque. b) Explain the construction and working of Universal motor and write down the application 8 of Universal motor. 9. a) Define the terms synchronous impedance and voltage regulation of an alternator explain 8 the synchronous impedance method to determine regulation of alternator. Draw and explain to phasor diagram of a loaded alternator for b) 8 lagging p.f. i) leading p.f. ii) iii) Unity p.f. OR 10. What are V – curve and inverted V curve of a synchronous motor? What are the main 8 a) characteristics of the synchronous motor? Explain the operation of a synchronous motor under b) 8 Constant load with excitation decrease. i) ii) Constant load with excitation increase. Draw the phasor diagram.

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5.

a)

Prove that torque developed